#### . . .

Check for updates

# Energy production assessment in a complex hydropower development

Andrei-Mugur Georgescu, Sanda-Carmen Georgescu, Georgiana Dunca, Diana Maria Bucur and Alexandru Aldea

# ABSTRACT

A complex multi-reservoir hydropower development (HPD) was studied from the point of view of energy production. The Gâlceag HPD system consists of three reservoirs, a high head hydropower plant (HPP) powered by two Francis turbines of 75 MW each, and a pumping station (PS) equipped with two centrifugal pumps of 10 MW each. The hydraulic system configuration is unusual: the PS discharge pipe conveys the water directly into HPP's penstock. Three operation scenarios were investigated: ① normal operation (with PS shutdown and HPP operational, as a conventional HPP), ② simultaneous operation (with both HPP and PS operational), and ③ pumped storage (with HPP shutdown and PS operational). Primarily, a numerical model was set up in EPANET to investigate the influence that the variation in the initial level of the HPP upstream reservoir has on the production of energy. In the sequel, a numerical model was derived and solved in GNU Octave to investigate the influence on the energy production of HPD due to initial levels of both the HPP upstream and downstream reservoirs. The results can be used in a decision support system to assess the overall operation of Gâlceag HPD based on water availability.

**Key words** | energy production, EPANET, GNU Octave, hydropower plant, pumped storage, variable level reservoir

#### Andrei-Mugur Georgescu Alexandru Aldea Hydraulics and Environmental Protection Department, Technical University of Civil Engineering of Bucharest, 124 Lacul Tei, RO-020396 Bucharest, Romania Sanda-Carmen Georgescu (corresponding author) Georgiana Dunca Diana Maria Bucur Hydraulics, Hydraulic Machinery and Environmental Engineering Department.

University Politehnica of Bucharest, 313 Splaiul Independentei, RO-060042 Bucharest, Romania E-mail: *carmen.georgescu@upb.ro* 

# INTRODUCTION

Due to massive and/or unexpected energy production from renewable sources, especially the fluctuant wind and solar power generation, conventional hydropower developments and pumped storage power developments became crucial in the stabilization of electric grids (Anagnostopoulos & Papantonis 2012; Boamba *et al.* 2014; Constantin *et al.* 2015; Pérez-Díaz *et al.* 2015). To fulfil this special purpose, hydropower units are often running at partial loads, instead of running at their best efficiency point, to cover a wide range of operating parameters variation. So, decision makers are interested to determine the appropriate variation range of those parameters to ensure safe operation of the system. Also, hydropower producers are interested to establish a strategy for bidding on the day-ahead electricity market, doi: 10.2166/hydro.2019.237 based on a decision support system that relies on the water availability (Bozorg Haddad *et al.* 2008; Jamshid Mousavi & Shourian 2010; Tica *et al.* 2017). Their goal is to settle and/or to optimize the amount of power that can be sold/bought in the spot market, as well as the amount of power that can be kept for ancillary services (Chazarra *et al.* 2016).

The present study focuses on a complex hydropower development (HPD), namely a pumped storage hydropower open system. In the attempt to assess the operation mode of that system, for different scenarios linked to the variation of water level in the reservoirs, the hydraulic analysis was performed based on an equivalent numerical model. The results, analysed in terms of the balance between the energy production and the energy consumption, can be implemented within a decision support system (Popa *et al.* 2008) to enhance the overall efficient operation of the hydropower system.

The numerical model attached to the studied HPD is described in the next section, which includes the HPD real scheme and the simplified model, the HPD operation scenarios, and the modelling approach. The results are presented and discussed in the third section, while the concluding remarks are drawn at the end of the paper.

## HPD NUMERICAL MODEL

## **HPD** scheme

Gâlceag HPD consists of three reservoirs, one high head hydropower plant (HPP), and one pumping station (PS). The resulting multi-reservoir system represents the upstream part of a hydropower cascade built on the Sebeş River in Romania (Popa *et al.* 2017). The above hydropower cascade contains three successive high head HPPs and ends by a low head (toe dam type) HPP (Hidroconstructia 2005). Gâlceag HPP is a peak load HPP, operating 2–3 h a day. The present study focuses exclusively on Gâlceag HPD, for which the hydraulic analysis is conducted during 1 h, assuming that the water exiting the HPP is retained in the nearby downstream reservoir. This assumption is equivalent with keeping shutdown, over 1 h, the other HPPs located downstream on the hydropower cascade.

The scheme of Gâlceag HPD is displayed in Figure 1 (left frame).

The main components of Gâlceag HPD are briefly described below, based on available technical data (Hidroconstructia 2005; Dunca *et al.* 2010, 2018; Bucur *et al.* 2014):

- Gâlceag HPP (year of commissioning: 1980) a high head underground HPP of 150 MW installed capacity and 260 GWh average annual energy production; it is powered by two Francis turbines, of 75 MW each, at 465 m head and 22.8 m<sup>3</sup>/s flow rate.
- Gâlceag PS (year of commissioning: 2003) a PS with two double-entry two-stage centrifugal pumps, each of 10 MW at 260 m pumping head and 3 m<sup>3</sup>/s discharge; PS elevation is 980 m above sea level (a.s.l.).

- Oaşa Reservoir the biggest upstream reservoir of the entire hydropower cascade on the Sebeş River, with an active storage capacity of 136.2 MCM at 1,255 m a.s.l. normal retention level; water is retained by Oaşa Dam (a rockfill dam 91 m height, with a reinforced concrete mask; year of commissioning: 1972).
- Cugir Reservoir a storage reservoir, used as PS suction reservoir (0.85 MCM active storage capacity, at the normal retention level of 1,007 m a.s.l.); water is retained by Cugir Dam (an arch dam 48 m height).
- Tău Reservoir the downstream reservoir within Gâlceag HPD scheme, with an active storage capacity of 21.3 MCM, at 790 m a.s.l. normal retention level; water is retained by Tău Dam (an arch dam 78 m height).
- Gâlceag HPP hydraulic circuit a headrace tunnel (3.7 m diameter and a total length of 8,456 m) connects Oaşa Reservoir to the penstock (2.8 m diameter and a length of 742 m, positioned at 32° from the vertical); at the downstream part of the headrace, there is a doublechamber surge tank; the valve house at the penstock inlet contains a butterfly valve with a diameter of 2.8 m; at the penstock outlet, a distributor conveys the water inside the powerhouse towards the turbines (before each turbine, a heavy-duty spherical valve is used for shutoff purposes); a tailrace tunnel (4 m diameter and a length of 610 m) conveys the water to Tău Reservoir.
- Gâlceag PS hydraulic circuit a headrace (2.8 m diameter and a length of 6,500 m) conveys water from the Cugir Reservoir to Gâlceag PS; at the downstream part of the headrace, before the PS powerhouse, there is a surge tank; the PS discharge pipe (1.3 m diameter and a length of 320 m) is connected to the upper part of the HPP's penstock at an elevation of 980 m a.s.l. (this unusual junction allows injection of the pumped water directly into the penstock); throttling valves (inside the PS) control the discharge.

#### **HPD model**

Gâlceag HPD model is presented in Figure 1 (right frame). The hydraulic analysis conducted in this paper does not involve transients, thus no surge tank is included in the equivalent scheme. The main components of Gâlceag

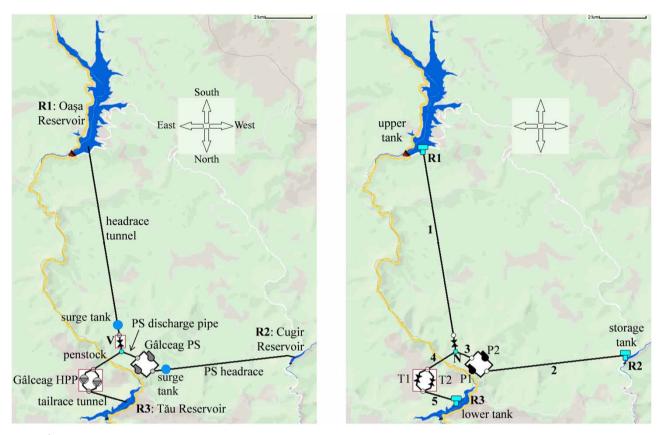


Figure 1 HPD scheme (left frame) versus equivalent model (right frame): Gâlceag HPP with Francis turbines T1 and T2; Gâlceag Pumping Station (PS) with pumps P1 and P2; Oaşa Reservoir (an upper tank R1); Cugir Reservoir (a storage tank R2); Tău Reservoir (a lower tank R3); pressurized pipes labelled as *j* = 1 ÷ 5 (HPP headrace tunnel *j* = 1; PS headrace *j* = 2; PS discharge pipe *j* = 3; HPP penstock *j* = 4; and HPP tailrace tunnel *j* = 5); valve house V; main junction N; surge tanks are not included in the equivalent scheme.

HPD equivalent scheme built-in EPANET are listed in the following (Dunca *et al.* 2018):

- Gâlceag HPP with Francis turbines T1 and T2 the turbines are modelled in EPANET by general purpose valves (GPVs) that introduce a given head loss-flow rate curve (Rossman 2000); to mimic a turbine, each GPV operates based on the turbine head-flow rate curve; the characteristic curves of the Francis turbines from Gâlceag HPP, namely the head-flow rate curve  $H_t = H_t(Q_t)$  and the efficiency-flow rate curve  $\eta_t = \eta_t(Q_t)$ , are displayed in Figure 2 (left frame); the head values  $H_t$  (in m), flow rate values  $Q_t$  (in m<sup>3</sup>/s), and efficiency values  $\eta_t$  (in %) were measured *in situ* (Bucur *et al.* 2012).
- Gâlceag PS with pumps P1 and P2, operating upon the pumping head-flow rate curve H<sub>p</sub> = H<sub>p</sub>(Q<sub>p</sub>) and efficiency-flow rate curve η<sub>p</sub> = η<sub>p</sub>(Q<sub>p</sub>), is displayed in

Figure 2 (right frame); the pumping head values  $H_p$  (in m), discharge values  $Q_p$  (in m<sup>3</sup>/s), and efficiency values  $\eta_p$  (in %) were measured *in situ* (Dunca *et al.* 2007).

- Three reservoirs (variable head water storages) denoted from R1 to R3, modelled in EPANET by storage tanks an upper tank R1 (Oaşa Reservoir), a storage tank R2 (Cugir Reservoir), and a lower tank R3 (Tău Reservoir); for each tank, the water level *z* (in m a.s.l.) varies upon the storage capacity *V* (in MCM), according to the capacity curve of each reservoir, as in Figure 3.
- Hydraulic circuit pressurized pipes labelled from *j* = 1 to *j* = 5, namely HPP headrace tunnel (*j* = 1), PS headrace (*j* = 2), PS discharge pipe (*j* = 3), HPP penstock (*j* = 4), and HPP tailrace tunnel (*j* = 5); main junction N; a butterfly valve inside the valve house, modelled in EPANET by a throttling control valve (TCV), kept fully open.

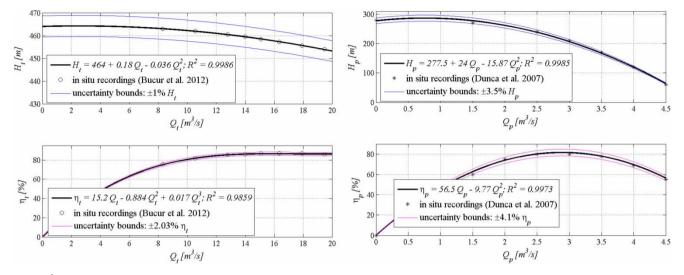


Figure 2 | Head-flow rate curves and efficiency-flow rate curves of the considered hydraulic machinery: Francis turbines (left frames) and centrifugal pumps (right frames).

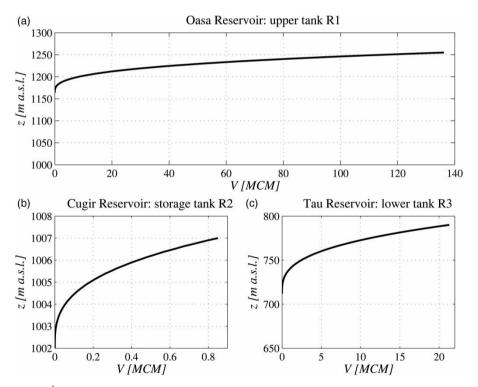


Figure 3 | Capacity curves attached to each tank (Dunca et al. 2018): (a) HPP upstream tank R1; (b) PS suction tank R2; and (c) HPP downstream tank R3.

#### **HPD** operation scenarios

Gâlceag HPD can operate according to the following scenarios, denoted from <sup>①</sup> to <sup>③</sup>, as shown in Figure 4.

 $\odot$  Normal operation scenario, where the HPP is fully operational, while the PS is shutdown – in this case, the

HPP is working as a conventional HPP, thus the water flows only from Oaşa Reservoir (tank R1) to Tău Reservoir (tank R3), passing through the turbines T1 and T2.

<sup>②</sup> Simultaneous operation scenario, where both the HPP and the PS are fully operational – in this case, the water pumped from Cugir Reservoir (tank R2) is injected

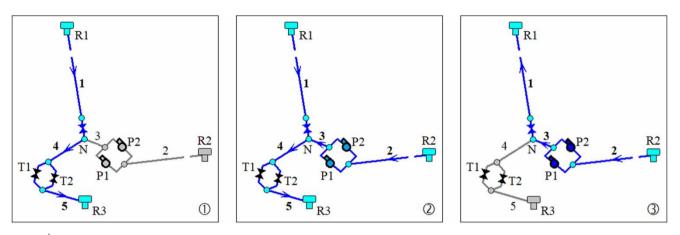


Figure 4 | Gâlceag HPD operation: ① normal operation scenario (HPP fully operational; PS shutdown); ② simultaneous operation scenario (HPP and PS fully operational); and ③ pumped storage scenario (HPP shutdown; PS fully operational).

into the penstock, being added to the water flowing from Oaşa Reservoir (R1); by increasing the flow rate through the turbines, the energy output of the HPP can be increased.

③ Pumped storage scenario, where the HPP is shutdown, while the PS is fully operational – in this case, the water is pumped from Cugir Reservoir (R2) to Oaşa Reservoir (R1) to increase the storage of the upstream reservoir.

Both normal operation and simultaneous operation scenarios correspond to peak load. The pumped storage scenario corresponds to off-peak when the electrical energy production exceeds the consumption within the National Power Grid.

#### Modelling approach

Primarily, for the proposed HPD, the numerical model was built in EPANET and run as an extended period simulation (EPS) (Van Zyl *et al.* 2006; Giustolisi *et al.* 2008; Todini 2011), starting from different initial levels in the upstream reservoir. The extended period simulations were performed using a hydraulic time step  $\delta t = 1$  min over a total time duration  $t_{max} = 60$  min. The 1-min time step was considered small enough with respect to the free surface area of the reservoirs (Giustolisi *et al.* 2012), so that the steady-state approach used by EPANET in EPS gives accurate results. Due to the fact that turbines were in fact modelled as valves, no efficiency-flow rate curve could be introduced in EPANET, so the calculations of power and energy production/consumption were performed in MS Excel, based on the flow rate and head values obtained from EPANET. This procedure proved useful when investigating only the influence of the initial level in the upstream reservoir (tank R1) on the HPD operation (Dunca et al. 2018). To provide a more complete analysis of the influence of the initial levels in the reservoirs on the production/consumption of energy in the HPD, the above-mentioned procedure was inadequate. In a first attempt to solve this problem, the EPANET model was imported in Bentley WaterGEMS, a commercial computer software that has a turbine object already defined. Unfortunately, this did not solve the problem, as for the turbine a head-flow rate curve can be inserted, but the efficiency of the turbine is considered constant, which would lead to the same procedure as the one used in EPANET for the computation of power and energy production. Finally, a GNU Octave script file was developed for this specific application, as presented in the sequel.

Tanks R1 ÷ R3 are set to be filled and/or emptied with respect to their capacity curves (volume curves), denoted  $z_{R1} = f(V_{R1})$ ,  $z_{R2} = f(V_{R2})$ , and  $z_{R3} = f(V_{R3})$ , plotted in Figure 3. The minimum level and maximum level setting values for each tank equal the minimum and normal retention levels of the selected reservoir. The initial level of each tank is set for each run, within the following ranges: for the upper tank R1, the initial level decreases, starting from the normal retention level of 1,255 m a.s.l., with a step of 1 m, down to 1,235 m a.s.l. (resulting in 21 values); for the storage tank R2, the initial level is kept constant and equal to the normal retention level of 1,007 m a.s.l. (being a small storage tank); for the lower tank R3, the initial level decreases with a step of 1 m, from the intermediate level of 780 m a.s.l., to the level of 760 m a.s.l. (resulting also in 21 values). Thus, for each of the first two operation scenarios, 441 runs can be performed, while the third scenario can be analysed upon 21 runs, yielding a total of 903 runs.

Selecting as initial conditions, at time  $t^{(0)} = 0$ , different initial water-level values  $z_{R1}(t^{(0)})$ ,  $z_{R2}(t^{(0)})$ , and  $z_{R3}(t^{(0)})$  in tanks R1 ÷ R3, the updated water levels  $z_{R1}(t^{(k)})$ ,  $z_{R2}(t^{(k)})$ , and  $z_{R3}(t^{(k)})$  are computed at the end of each time step, i.e. at time  $t^{(k)} = (t^{(k-1)} + \delta t)$ , for  $k = 1 \div 60$ , where  $t^{(60)} = t_{max}$ .

The code allows running a steady-state hydraulic analysis on each time step  $\delta t$ , yielding a snapshot solution at the beginning of the time step, at time  $t^{(k-1)}$  (here  $k = 1 \div 60$ ). So, the EPS involves computing successive snapshot solutions, connected from time  $t^{(k-1)}$  to  $t^{(k)}$  through mass balance computations. This procedure allows to decrease or increase the water volume  $V^{(k-1)}$  in any tank, and the water level  $z^{(k-1)} = f(V^{(k-1)})$ , upon the direction of the flow rate  $Q^{(k-1)}$ . The volume variation from time  $t_{k-1}$  to  $t_k$ can be approximated as  $\delta V^{(k)} = (V^{(k)} - V^{(k-1)}) = \pm Q^{(k-1)} \cdot \delta t$ , where the negative variation corresponds to the outflow (tank emptying), while the positive variation corresponds to inflow (tank filling).

A system of nonlinear equations can be derived for Gâlceag HPD, at time  $t^{(k-1)}$  (for  $k = 1 \div 60$ ), according to each operation scenario (Figure 4). The system consists of energy balances between two successive nodes, and continuity equations at nodes, e.g. as described within the system (1) of Giustolisi *et al.* (2012), where one must consider that pumps run at a constant speed, and turbines are modelled by minor losses. Efficiency curves can be attached to the pumps to complete the cited equations system. Such a system of nonlinear equations can be solved in EPANET using the Global Gradient Algorithm (Todini & Pilati 1988).

Potential instabilities may appear in EPANET computations, when dealing with EPS and multiple tanks that are not nearly far enough (Todini 2011). In our model, tanks R1  $\div$  R3 are quite far apart from one another, and their storage capacity is huge with respect to the water volume variation due to the inflow/outflow, so EPANET can provide trustworthy solutions (Dunca *et al.* 2018), but as already mentioned, each solution requests post-processing outside EPANET. The solutions presented in this paper are computed using the function *fsolve* of GNU Octave (Eaton *et al.* 2019), also available in MATLAB<sup>®</sup> (MathWorks 2019).

To perform computations using the built-in function *fsolve*, the nonlinear system of equations attached to Gâlceag HPD will be simplified in the sequel, to reduce the number of equations. The system can be simplified, assuming that both turbines run with identical loads when the HPP is fully operational, and both pumps run with identical duty points when the PS is fully operational. To obtain the solution with *fsolve*, the nonlinear system will be inserted in a user-defined function, with two arguments (Georgescu & Georgescu 2014), namely a vector containing the unknowns of the problem, and a vector containing three parameters, namely the initial water levels in tanks R1  $\div$  R3.

The system will be derived for the second scenario, related to simultaneous operation of HPP and PS, being the most complex one. Simplifications will be mentioned further for the first and third scenarios.

Thus, for scenario ②, pointing on the simultaneous operation, where both HPP and PS are fully operational (Figure 4, middle frame), the nonlinear system of equations is written at time  $t^{(k-1)}$ , for  $k = 1 \div 60$ , as follows:

$$\begin{cases} z_{\text{R1}}^{(k-1)} = z_{\text{R3}}^{(k-1)} + H_t^{(k-1)} \\ + R_1^{(k-1)} (Q_1^{(k-1)})^2 + \left(\sum_{j=4}^5 R_j^{(k-1)}\right) (2Q_t^{(k-1)})^2 \\ z_{\text{R2}}^{(k-1)} + H_p^{(k-1)} = z_{\text{R3}}^{(k-1)} + H_t^{(k-1)} \\ + \left(\sum_{j=2}^5 R_j^{(k-1)}\right) (2Q_p^{(k-1)})^2 \\ + \left(\sum_{j=4}^5 R_j^{(k-1)}\right) (2Q_t^{(k-1)})^2 \\ Q_2^{(k-1)} = Q_5^{(k-1)} = 2Q_p^{(k-1)} \\ Q_1^{(k-1)} + Q_3^{(k-1)} = Q_4^{(k-1)} \\ Q_4^{(k-1)} = Q_5^{(k-1)} = 2Q_t^{(k-1)} \end{cases}$$
(1)

where  $R_i$  (in s<sup>2</sup>/m<sup>5</sup>) is the hydraulic resistance of pipes with index  $j = 1 \div 5$ ,  $Q_i$  is the flow rate on pipes (in m<sup>3</sup>/s),  $Q_t$  is the flow rate through one turbine,  $Q_p$  is the discharge of one pump,  $H_t$  is the turbine head, and  $H_p$  is the pumping head (in m). Darcy–Weisbach formula is used to compute head losses on pipes, where the friction factor is defined by the explicit formula of Swamee & Jain (1976), for an equivalent roughness of 1 mm on all pipes. The hydraulic resistances take into account minor losses on pipes, which were inserted through equivalent length or diameters of some pipes – thus, the real length of four pipes was increased ( $L_1 = 8.5$  km,  $L_3 = 340$  m,  $L_4 = 750$  m, and  $L_5 = 1$  km), and one diameter was decreased ( $D_5 = 2.8$  m).

The turbine head-flow rate curve  $H_t = H_t(Q_t)$  and efficiency-flow rate curve  $\eta_t = \eta_t(Q_t)$ , plotted in Figure 2 (left frame), with  $\eta_t$  (in %), can be fitted by the following polynomial regressions:

$$\begin{cases} H_t = 464 + 0.18Q_t - 0.036Q_t^2\\ \eta_t = 15.2Q_t - 0.884Q_t^2 + 0.017Q_t^3 \end{cases}$$
(2)

The pumping head-flow rate curve  $H_p = H_p(Q_p)$  and pump efficiency-flow rate curve  $\eta_p = \eta_p(Q_p)$ , plotted in Figure 2 (right frame), with  $\eta_p$  (in %), can also be fitted by polynomial regressions (Dunca *et al.* 2018):

$$\begin{cases} H_p = 277.5 + 24Q_p - 15.87Q_p^2\\ \eta_p = 56.5Q_p - 9.77Q_p^2 \end{cases}$$
(3)

All four regression curves defined by (2) and (3) are displayed in Figure 2, together with the corresponding  $R^2$  values, and the limits of the total uncertainty bandwidth.

The dependencies  $H_t = H_t(Q_t)$  from (2) and  $H_p = H_p(Q_p)$  from (3), considered at time  $t^{(k-1)}$ , are inserted into the system (1). Due to the friction factor formula, the resulting system is highly nonlinear. The solution of (1), consisting of the flow rates through one turbine,  $Q_t^{(k-1)}$ , and one pump,  $Q_p^{(k-1)}$ , yields the flow rates on all five pipes at time  $t^{(k-1)}$ .

Next, all storage capacities (volumes) values and waterlevel values at time  $t^{(k)}$  are computed as follows:

$$\begin{cases} V_{R1}^{(k)} = V_{R1}^{(k-1)} - Q_1^{(k-1)} \delta t \\ \Rightarrow z_{R1}^{(k)} = f(V_{R1}^{(k)}) \\ V_{R2}^{(k)} = V_{R2}^{(k-1)} - Q_2^{(k-1)} \delta t \\ \Rightarrow z_{R2}^{(k)} = f(V_{R2}^{(k)}) \\ V_{R3}^{(k)} = V_{R3}^{(k-1)} + Q_5^{(k-1)} \delta t \\ \Rightarrow z_{R3}^{(k)} = f(V_{R3}^{(k)}) \end{cases}$$
(4)

Iterations continue up to k = 60.

The values of the flow rate through one turbine at time  $t^{(k-1)}$ , for  $k = 1 \div 60$ , allow computing the corresponding head and efficiency values (2), thus the turbine power  $P_t$  (in MW) and the energy production  $E_t$  (in MWh), at each time step in hours ( $\delta t = 1/60$  h):

$$\begin{cases} P_t^{(k-1)} = (\rho g Q_t^{(k-1)} H_t^{(k-1)} \eta_t^{(k-1)}) \times 10^{-6} \\ \Rightarrow E_t^{(k-1)} = P_t^{(k-1)} \delta t \end{cases}$$
(5)

where  $\rho$  is the water density (in kg/m<sup>3</sup>), g is the gravity (in m/s<sup>2</sup>),  $\eta_t$  is inserted as dimensionless value, and  $1 \times 10^{-6}$  is the conversion factor from W to MW.

The energy production  $E_{\text{HPP}}|_{(2)}$  in Gâlceag HPP, where two turbines are identically loaded, is finally obtained in MWh, for the considered run attached to the operation scenario 0, as follows:

$$E_{\rm HPP}|_{(2)} = 2\sum_{k=1}^{60} E_t^{(k-1)}$$
(6)

Similarly, the values of the discharge of one pump at time  $t^{(k-1)}$ , for  $k = 1 \div 60$ , allow computing the corresponding pumping head and efficiency values (3), thus the pump power  $P_p$  (in MW) and the energy consumption  $E_p$  (in MWh), on each time step in hours ( $\delta t = 1/60$  h):

$$\begin{cases} P_p^{(k-1)} = \left(\frac{\rho g Q_p^{(k-1)} H_p^{(k-1)}}{\eta_p^{(k-1)}}\right) \times 10^{-6} \\ \Rightarrow E_p^{(k-1)} = P_p^{(k-1)} \delta t \end{cases}$$
(7)

where  $\eta_p$  is inserted as dimensionless value and  $1 \times 10^{-6}$  is the conversion factor from W to MW.

The energy consumption  $E_{PS}|_{(2)}$  in Gâlceag PS, where two pumps are working, is finally computed in MWh, for the considered run attached to the operation scenario @, as follows:

$$E_{\rm PS}|_{(2)} = 2\sum_{k=1}^{60} E_p^{(k-1)}$$
(8)

The global energy production  $E_{\text{HPD}}|_{(2)}$  in Gâlceag HPD, within the second scenario where both turbines and both

pumps are working simultaneously, can be finally computed in MWh, as follows:

$$E_{\rm HPD}|_{(2)} = E_{\rm HPP}|_{(2)} - E_{\rm PS}|_{(2)} \tag{9}$$

For scenario  $\odot$  pointing on normal operation, where the HPP is fully operational, and the PS is shutdown (Figure 4, left frame), the system of nonlinear equations (1), for  $k = 1 \div 60$ , is simplified to:

$$\begin{cases} z_{\text{R1}}^{(k-1)} = z_{\text{R3}}^{(k-1)} + H_t^{(k-1)} \\ + \left(\sum_{j=1,4,5} R_j^{(k-1)}\right) (2Q_t^{(k-1)})^2 \\ Q_1^{(k-1)} = Q_4^{(k-1)} = Q_5^{(k-1)} = 2Q_t^{(k-1)} \end{cases}$$
(10)

The storage capacities and water levels (4) at time  $t^{(k)}$  are also simplified for scenario  $\mathbb{O}$ , as follows:

$$\begin{cases} V_{R1}^{(k)} = V_{R1}^{(k-1)} - Q_1^{(k-1)} \delta t \\ \Rightarrow z_{R1}^{(k)} = f(V_{R1}^{(k)}) \\ V_{R3}^{(k)} = V_{R3}^{(k-1)} + Q_5^{(k-1)} \delta t \\ \Rightarrow z_{R3}^{(k)} = f(V_{R3}^{(k)}) \end{cases}$$
(11)

The energy production  $E_{\text{HPP}|(1)}$  in Gâlceag HPP is computed in MWh, for the considered run attached to the normal operation scenario  $\bigcirc$  where two turbines are operating, as follows:

$$E_{\rm HPP}|_{(1)} = 2\sum_{k=1}^{60} E_t^{(k-1)}$$
(12)

The point of interest is to compute the energy gain  $\Delta E_{\text{HPD}}$  defined as follows:

$$\Delta E_{\rm HPD} = E_{\rm HPD}|_{(2)} - E_{\rm HPP}|_{(1)} \tag{13}$$

to compare the first two scenarios. Positive energy gain values indicate the range of initial water-level values, for which the simultaneous operation (scenario <sup>(2)</sup>) overcomes the normal operation (scenario <sup>(3)</sup>), from the profit (energy generation) point of view.

Finally, for scenario ③, pointing on pumped storage operation, where the HPP is shutdown, and the PS is fully operational (Figure 4, right frame), the system (1), for  $k = 1 \div 60$ , is modified as follows:

$$\begin{cases} z_{\text{R2}}^{(k-1)} + H_p^{(k-1)} = z_{\text{R1}}^{(k-1)} \\ + \left(\sum_{j=1}^3 R_j^{(k-1)}\right) (2Q_p^{(k-1)})^2 \\ Q_2^{(k-1)} = Q_3^{(k-1)} = Q_1^{(k-1)} = 2Q_p^{(k-1)} \end{cases}$$
(14)

The storage capacities and water levels (4) at time  $t^{(k)}$  are modified for scenario ③, as follows:

$$\begin{cases} V_{R1}^{(k)} = V_{R1}^{(k-1)} + Q_1^{(k-1)} \delta t \\ \Rightarrow z_{R1}^{(k)} = f(V_{R1}^{(k)}) \\ V_{R2}^{(k)} = V_{R2}^{(k-1)} - Q_2^{(k-1)} \delta t \\ \Rightarrow z_{R2}^{(k)} = f(V_{R2}^{(k)}) \end{cases}$$
(15)

As expressed in (15), within the pumped storage operation, the upper tank R1 is filled.

The energy consumption  $E_{PS}|_{(3)}$  in Gâlceag PS, where two pumps are working within scenario ③, is finally computed in MWh,

$$E_{\rm PS}|_{(3)} = 2\sum_{k=1}^{60} E_p^{(k-1)}$$
(16)

based on the procedure described for scenario  $\bigcirc$ , where the pumped flow rate obtained from (14) is inserted into Equations (3) and (7).

Due to the lack of experimental data, the uncertainties induced by the proposed mathematical model over the energy assessment cannot be estimated.

#### **RESULTS AND DISCUSSION**

When the Gâlceag HPD model was firstly created and run in EPANET (Dunca *et al.* 2018), it became obvious that the pumped storage operation (scenario ③) is possible only over a limited time period since the capacity of the PS suction reservoir (storage tank R2) is far too small with respect to the capacity of the HPP upstream reservoir (upper tank R1) – the ratio between the active storage capacities of those reservoirs is of 1/160. As highlighted by Dunca *et al.* (2018), emptying the tank R2 by pumping, starting from the normal retention level (where the reservoir is full), will account only for about 1.3% of the volume of the upper tank R1 corresponding to the average annual minimum water level.

This is the reason for which all computations related to scenarios ③ and ③ (where the PS is fully operational) were performed for a unique value of the initial water-level  $z_{R2}(t^{(0)})$  in the storage tank R2, namely the maximal (normal retention) level.

Results for computations started with the initial water level equal to the normal retention level in both HPP upstream and PS suction reservoirs, and equal to 770 m a.s.l. in HPP's downstream reservoir, show that (Dunca *et al.* 2018):

- the power delivered only by the turbines (no pumps working) is about 115 MW;
- the overall power delivered to the electric grid when all pumps and turbines are working (obtained as the difference between the power provided by the turbines and the power consumed by the pumps) is of about 113 MW;
- the power required to pump water from the PS suction reservoir to the HPP upstream reservoir is about 15.5 MW.

The relatively small difference between the first scenario (normal operation) and the second scenario (simultaneous operation) provided a clue as to what could be the real purpose of such a combined facility. A comparison among the values obtained for the overall energy production in the scenarios ① and ②, when the initial level  $z_{R1}$  in the HPP upstream reservoir was varied between the normal retention level and the average annual minimum level, while the other initial levels were set to  $z_{\text{R2}} = 1,007$  m a.s.l. and  $z_{\text{R3}} = 770$  m a.s.l., is shown in Figure 5. It is clear from Figure 5, that for an initial water level in the downstream reservoir (770 m a.s.l.), for some values of the water level in the HPP upstream reservoir, the overall quantity of energy provided by the system when all pumps and turbines are working, exceeds the quantity that would be provided if only the turbines would work. This occurs for water levels in the HPP upstream reservoir between 1,252 and 1,238 m a.s.l. Differences are relatively small, so in order to increase the accuracy, we present in Figure 6, the gain in energy, obtained when pumps and turbines work together -i.e.the differences between the overall energy produced in scenario 2 and the energy produced in scenario 1 (Dunca et al. 2018). Obviously, positive values represent a gain in the overall energy delivered by the system. The maximum gain in energy is of about 2,650 kWh, obtained when the initial water level in the HPP upstream reservoir is of 1,242 m a.s.l.

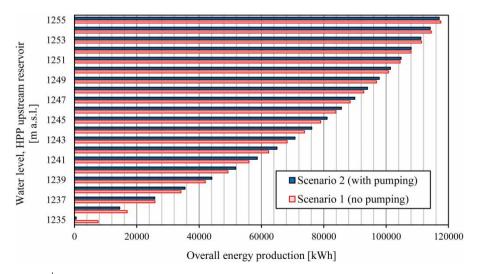
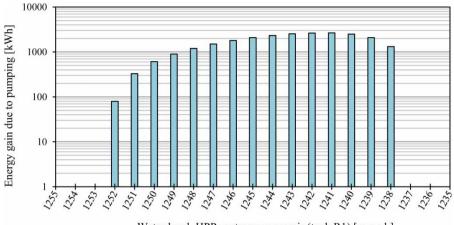


Figure 5 | Overall energy production (kWh):  $E_{HPD|(2)}$  for scenario (2) and  $E_{HPP|(1)}$  for scenario (2), obtained at different values of the initial water level in the HPP upstream reservoir – tank R1, for the initial water level  $z_{R3} = 770$  m a.s.l. in the HPP downstream reservoir – tank R3.



Water level, HPP upstream reservoir (tank R1) [m a.s.l.]

Figure 6 | Energy gain (kWh) due to pumping for various levels in the HPP upstream reservoir, for the initial water level z<sub>R3</sub> = 770 m a.s.l. in the HPP downstream reservoir.

The behaviour of the system can be explained as follows. On one hand, the flow rate through the turbines is increased when pumps and turbines work together (scenario ③), with respect to the case when only turbines are used (scenario ①). On the other hand, the flow through the pumps is also increased as the level in the HPP upstream reservoir decreases.

For some intermediate values of the initial level in the upper tank R1, the flow increase shifts the values of the efficiency of both turbines and pumps towards bigger values, leading to the more efficient production of energy in the turbines and more energy introduced by the pumps in the flow.

According to Figure 6, for the initial water level of 1,242 m a.s.l. in the tank R1, the gain in energy reaches a

maximum. This energy gain does not necessarily mean that the system is more efficient.

In this respect, it may seem like a good idea to use the pumps when the initial water level in the HPP upstream reservoir is between 1,252 and 1,238 m a.s.l., as more energy is provided to the electric grid.

As already stated, 21 equally spaced values of the initial water level were set (successively and decreasingly) for each of the upper tank R1 and lower tank R3, starting from the normal retention level of R1, and from an intermediate level of R3.

The results obtained for the energy production  $E_{\text{HPP}}|_{(1)}$ in Gâlceag HPP for scenario ① (only HPP in operation),

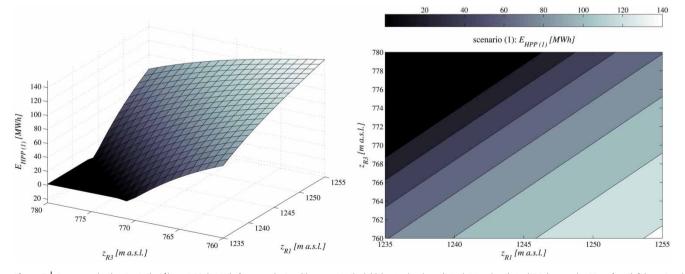


Figure 7 | Energy production  $E_{HPP|(1)}$  in Gâlceag HPP, in MWh, for scenario ①, with respect to the initial water levels  $z_{R1}$  in tank R1 and  $z_{R3}$  in tank R3, in m a.s.l. – 3D surface (left image) and its corresponding 2D contour plot (right image).

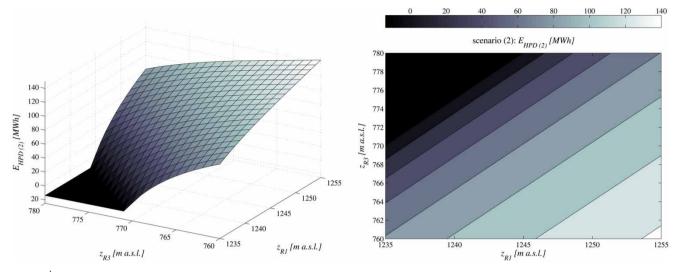


Figure 8 | Global energy production E<sub>HPD</sub>(z) in Gâlceag HPD, in MWh, for scenario ②, with respect to the initial water levels z<sub>R1</sub> in tank R1 and z<sub>R3</sub> in tank R3, in m a.s.l. – 3D surface (left image) and its corresponding 2D contour plot (right image).

and the global energy production  $E_{\text{HPD}|(2)}$  in Gâlceag HPD for scenario <sup>(2)</sup> (both HPP and PS in operation), are presented in Figures 7 and 8, as 3D surfaces and corresponding 2D contour plots, with respect to the variation of the initial water levels  $z_{\text{R1}}$  in the tank R1 and  $z_{\text{R3}}$  in the tank R3. The resulting energy gain  $\Delta E_{\text{HPD}}$ , defined by (13) for the entire HPD, to compare the simultaneous operation (scenario <sup>(2)</sup>) and the normal operation (scenario <sup>(3)</sup>), is presented in Figure 9, as 3D surface and attached 2D contour plot, as function of the initial water levels  $z_{\text{R1}}$  and  $z_{\text{R3}}$ . The variation of the energy gain  $\Delta E_{\text{HPD}}$  with respect to the initial water level  $z_{\text{R1}}$  in tank R1, is plotted in Figure 10, for three values of the initial level in tank R3, namely  $z_{\text{R3}}(t^{(0)}) = \{770; 765; 760\}$  m a.s.l.

The difference between the water levels in the upper tank R1 and the lower tank R3 is the gross head  $H_g$  of the HPP. The computed data shows that the energy gain (Figure 9) is always positive for some specific values of the initial gross head, e.g. for  $H_g \in [469; 477]$  m, attached to the initial water levels  $z_{R1}(t^{(0)}) \le 1,237$  m a.s.l. and

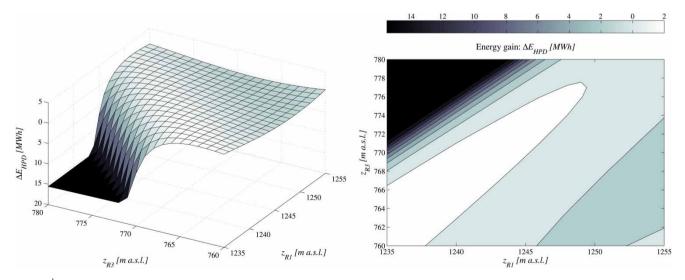
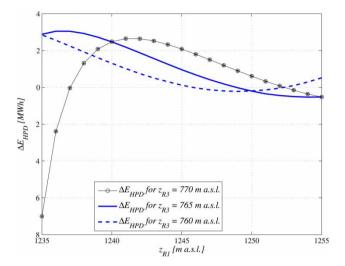


Figure 9 | Energy gain  $\Delta E_{HPD}$ , in MWh, between the simultaneous operation (scenario O) and the normal operation (scenario O), with respect to the initial water levels  $z_{R1}$  in tank R1 and  $z_{R3}$  in tank R3, in m a.s.l. – 3D surface (left image) and its corresponding 2D contour plot (right image).



**Figure 10** Energy gain  $\Delta E_{HPD}$ , in MWh, between the simultaneous operation (scenario ③) and the normal operation (scenario ④), with respect to the initial water level  $z_{R1}$  in tank R1 for three values of the initial level in tank R3:  $z_{R3} = \{770, 765, 760\}$  m a.s.l.

 $z_{\rm R3}(t^{(0)}) \le 766$  m a.s.l. Other specific values of  $H_g$  attached to positive  $\Delta E_{\rm HPD}$  can be retrieved from the narrow white band on the right frame of Figure 9.

## CONCLUSIONS

This paper presents the numerical modelling of a HPP coupled to a PS, in a complex HPD existing in Romania. Measured characteristic curves of the pumps and the hydraulic turbines were used in the model.

Three main scenarios were tested: ① only the HPP in operation, as a conventional HPP; ② both HPP and PS in operation (where the pumped water is discharged directly into the penstock, increasing the flow rate towards the HPP); and ③ only PS in operation (where water is pumped from the PS suction reservoir to supply the HPP upstream reservoir, through the HPP penstock and headrace). The initial water levels in the HPP upstream and downstream reservoirs were varied (over 20 m, by 20 equally spaced steps), starting from the normal retention level, and an intermediate level, respectively.

The simulations give the energy production and/or consumption in the studied cases. The results show that for some predefined ranges of water levels in the HPP upstream and downstream reservoirs, more energy is generated if turbines and pumps work simultaneously (scenario <sup>©</sup>). For a more complete analysis, further work is necessary to assess the partial operation of the HPD (e.g. only one turbine in operation and/or only one pump, or one turbine and both pumps).

Although the accuracy of the model is difficult to ascertain without measured values of energy production and consumption at the HPD, in close correlation to water levels at the reservoirs, the presented methodology, i.e. using on-site measured curves for pumps and turbines in a numerical model of a pipe network, yields usually better results than using catalogue curves (performances of hydraulic machineries decrease in time, while catalogue curves are determined for new items). Moreover, with the advent of renewable energies that have a more unsteady production in the energy mix, the role of hydropower as a regulator of the power system has increased. For such purposes, the analysis could prove useful.

The results can be used within a decision support system, to assess the overall operation of the HPD upon the water availability (water levels in reservoirs), in order to evaluate the amount of power that can be used for power generation.

#### REFERENCES

- Anagnostopoulos, J. S. & Papantonis, D. E. 2012 Study of pumped storage schemes to support high RES penetration in the electric power system in Greece. *Energy* **45** (1), 416–423.
- Boamba, C. E., Mirea, C., Eremia, M. & Tristiu, I. 2014 Influence of renewable sources on Romanian power system. UPB Scientific Bulletin, Series C 76 (4), 191–198.
- Bozorg Haddad, O., Afshar, A. & Mariño, M. A. 2008 Honey-bee mating optimization (HBMO) algorithm in deriving optimal operation rules for reservoirs. *Journal of Hydroinformatics* 10 (3), 257–264.
- Bucur, D. M., Dunca, G., Isbasoiu, E. C., Calinoiu, C. & Rosioru, O. T. 2012 Analysis of operating parameters during normal and transient regimes of a high head hydro power plant. UPB Scientific Bulletin, Series D 74 (1), 51–58.
- Bucur, D. M., Dunca, G., Cervantes, M. J., Calinoiu, C. & Isbasoiu, E. C. 2014 Simultaneous transient operation of a high head hydro power plant and a storage pumping station in the same hydraulic scheme. *IOP Conference Series: Earth and Environmental Science* 22, 042015.
- Chazarra, M., Pérez-Díaz, J. I., García-González, J. & Helseth, A. 2016 Modeling the real-time use of reserves in the joint energy and reserve hourly scheduling of a pumped storage plant. *Energy Procedia* 87, 53–60.

- Constantin, C., Eremia, M. & Bulac, C. 2015 Power system transient stability improvement using series FACTS devices. *UPB Scientific Bulletin, Series C* 77 (3), 259–268.
- Dunca, G., Bucur, D. M., Isbasoiu, E. C. & Calinoiu, C. 2007 Transient behavior analysis. Study case: pumping station Gâlceag. UPB Scientific Bulletin, Series C 69 (4), 651–658.
- Dunca, G., Muntean, S. & Isbasoiu, E. C. 2010 Analysis of the flow field into a two stages and double entry storage pump taking into account two geometries of stator blades. *IOP Conference Series: Earth and Environmental Science* **12**, 012016.
- Dunca, G., Bucur, D. M., Aldea, A., Georgescu, A.-M. & Georgescu, S.-C. 2018 EPANET modelling of a high head pumped-storage hydropower facility. *MDPI Proceedings* 2 (11), 608 (Proceedings of EWaS3 2018, https://doi.org/10. 3390/proceedings2110608).
- Eaton, J. W., Bateman, D., Hauberg, S. & Wehbring, R. 2019 GNU Octave. A High-Level Interactive Language for Numerical Computations, 5th edn. Octave 5.1.0, Free Software Foundation, Boston, USA. https://octave.org/octave.pdf (accessed 12 July 2019).
- Georgescu, S.-C. & Georgescu, A.-M. 2014 Calculul Retelor Hidraulice cu GNU Octave (Hydraulic Networks Analysis Using GNU Octave). Printech Press, Bucharest, Romania.
- Giustolisi, O., Kapelan, Z. & Savic, D. A. 2008 Extended period simulation analysis considering valve shutdowns. *Journal of Water Resources Planning and Management* 134 (6), 527–537.
- Giustolisi, O., Berardi, L. & Laucelli, D. 2012 Generalizing WDN simulation models to variable tank levels. *Journal of Hydroinformatics* 14 (3), 562–573.
- Hidroconstructia, S. A. 2005 Projects/ Hydroenergetics/ Sebes Branch. http://www.hidroconstructia.com/eng/projecte. html (accessed 12 July 2019).
- Jamshid Mousavi, S. & Shourian, M. 2010 Capacity optimization of hydropower storage projects using particle swarm

optimization algorithm. Journal of Hydroinformatics 12 (3), 275–291.

- MathWorks 2019 MATLAB Documentation/Optimization Toolbox/Systems of Nonlinear Equations/fsolve. https:// www.mathworks.com/help/optim/ug/fsolve.html (accessed 12 July 2019).
- Pérez-Díaz, J. I., Chazarra, M., García-González, J., Cavazzini, G. & Stoppato, A. 2015 Trends and challenges in the operation of pumped-storage hydropower plants. *Renewable and Sustainable Energy Reviews* 44, 767–784.
- Popa, R., Dragomirescu, A. & Popa, B. 2008 Decision support program for long term production planning of hydro-power plants with major reservoirs. UPB Scientific Bulletin, Series D 70 (4), 137–146.
- Popa, F., Popa, B. & Popescu, C. 2017 Assessment of pumped storage plants in Romania. *Energy Procedia* **112**, 473–480.
- Rossman, L. 2000 EPANET 2 Users Manual. EPA/600/R-00/057, U.S. Environmental Protection Agency (EPA), Cincinnati, OH, USA.
- Swamee, P. K. & Jain, A. K. 1976 Explicit equations for pipe flow problems. *Journal of the Hydraulics Division* **102** (5), 657–664.
- Tica, E. I., Popa, B. & Popa, R. 2017 Annual performance estimation of a multireservoir system including a pumped storage plant for the mean hydrological year. *Journal of Energy Engineering* 143 (6), 04017058.
- Todini, E. 2011 Extending the global gradient algorithm to unsteady flow extended period simulations of water distribution systems. *Journal of Hydroinformatics* **13** (2), 167–180.
- Todini, E. & Pilati, S. 1988 A gradient method for the solution of looped pipe networks. In: *Computer Applications in Water Supply*, Vol. 1 (B. Coulbeck & C.-H. Orr, eds). Wiley, New York, pp. 1–20.
- Van Zyl, J., Savic, D. A. & Walters, G. A. 2006 Explicit integration method for extended-period simulation of water distribution systems. *Journal of Hydraulic Engineering* 132 (4), 385–392.

First received 15 July 2019; accepted in revised form 2 October 2019. Available online 22 October 2019